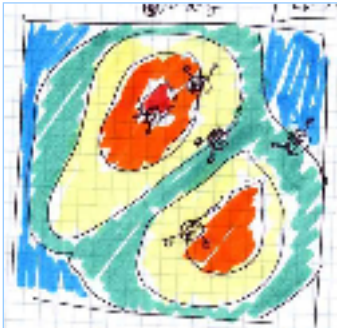


FERAL DOG DATASHEET

- Species Name: Mr. Bojangles
- Reverse Engineer: Joe Aphinyanaphongs
- Logic Development



Dogs are color coordinated and are assigned certain "ranges" of sensor activity to monitor and mark. - Say, for example, that the area we covered had an arbitrary of sensor activity that ranged from 0 to 50 (0 being innocuous and 50 being the most severe) - If the location we chose has'd a consistence grandiant of activity (like radiation...something that remains still and gradual, and is not affected by wind like a gas would be), then the dogs, after they have been programmed their respective "ranges" can be let loose to: (1) locate their allotted ranges; once found the dogs will "lock" and isolate themselves in the area designated by their range. (2) remain and travel within the range and collect data.

It is important to understand toys because of the un-harnessed abilities they have. If you can learn to utilize every part of the toy, you can manipulate them to get the results or actions that you want. Using something that is already made is much more efficient than creating something from scratch. Hence the reason we are using robotic dogs and building from there, instead of building entirely new ones.