

# Longdata notes: Sept. 8. 2003 - Enders, ch. 1 - Difference equations

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Enders is very clear, so I only need emphasize what is really important

- Notation:  $\Delta y_t = y_t - y_{t-1}$
- Difference between structural and reduced form of a model; reduced form for  $y$  has only lagged values of  $y$  and forcing (see below) variables
- Forcing variables: what we might call exogenous. Can either be  $x$ s that are not caused by  $y$  but cause  $y$ , or errors. At present, either are the same
- Solution to reduced form: write  $y_t$  in terms of forcing process and initial conditions on  $y$  ( $y_0$ ), no general lagged values of  $y$  in solution
- Notion of equilibrium ( $y_t^E = y_{t+1}^E$ )
- How does system get to equilibrium
- Is equilibrium stable?
- Memory of process - role of  $y_0$  in determining  $y_t$  when  $t$  is big
- Stability of system - does it explode as  $t$  grows?
- Solution by forward iteration from known  $y_0$
- Solution by backward iteration - at some point distant past doesn't matter if memory is not too long
- Hard to do for other than very simple model
- Impact multiplier -  $\frac{\partial y_t}{\partial x_t}$  = first derivative of  $y$  wrt forcing variable 11. One period impact multiplier -  $\frac{\partial y_{t+1}}{\partial x_t}$  = first derivative of the lead of  $y$  wrt forcing variable 12. Impulse response function - graph of all impact multiplier for all leads

## More general method

Details in Enders, 1-6

- For equation  $y_t = a_1 y_{t-1} + a_2 y_{t-2} + x_t$  where  $x$  is an arbitrary forcing process

- First solve the homogenous equation  $y_t - a_1y_{t-1} - a_2y_{t-2} = 0$
- if  $S$  is a solution, so is  $Cy^S$  and if  $y^S$  and  $y^T$  is a solution, so is  $y^S + y^T$
- For n'th order equation, there are two general solutions and any linear combination is also a solution
- Try  $y_t = \alpha^t$
- Then  $\alpha^2 - a_1\alpha - a_2 = 0$
- Simple quadratic, solve for two values of  $\alpha$ , characteristic roots by high school formula
- If roots unequal, done.
- Each root must be less than one, else unstable
- If roots equal (unlikely in practice), solutions are  $\frac{a_1}{2}t$  and  $t\frac{a_1}{2}$ . Stability if  $|a_1| < 2$
- If roots imaginary, then resort to DeMoivre's Theorem to get result as on p. 27